

# A Bibliography on Control of Piecewise-Affine Hybrid Systems on Polytopes

Jan H. van Schuppen

Van Schuppen Control Research

Gouden Leeuw 143, 1103 KB Amsterdam, The Netherlands

Email [jan.h.van.schuppen@xs4all.nl](mailto:jan.h.van.schuppen@xs4all.nl)

September 15, 2017

A bibliography is provided on control of piecewise-affine hybrid systems on polytopes and closely related topics. This document is made for the participants of a Ph.D. School on Cyber-Physical System held in Verona, Italy during several days of September 2017.

## 1 Introduction

The reader finds in this document a structured list of references on control of piecewise-affine hybrid systems on polytopes and related topics.

This document is produced for the participants of the Ph.D. School on Cyber-Physical Systems scheduled for 11-15 September 2017 at the Department of Computer Science of the University of Verona in Verona, Italy.

The main references for the lectures of the author of this documents are [80, 76, 48]. Of the three references mentioned above, the first one deals only with affine systems on polytopes, the second with piecewise-affine hybrid systems on simplices, and the last one with output feedback of piecewise-affine hybrid systems on polytopes. The acronym PAHSP stands for piecewise-affine hybrid systems on polytopes. The results were developed at the research institute CWI in Amsterdam, The Netherlands, by the Research Group Control and System Theory, in particular by Pieter Collins, Luc Habets, and Jan H. van Schuppen.

Others have developed the approach in new directions.

The reader should note that almost all references are for continuous-time hybrid systems. When discrete-time systems are referred to this is explicitly mentioned.

## 2 List of References on Control of Piecewise-Affine Hybrid Systems on Polytopes (PAHSP)

**Papers on control of PAHSP by the CWI Research Group Control and System Theory** The initial paper on control of a piecewise-affine hybrid system on polytopes in which the control-to-facet approach was indirectly formulated is [147]. The main papers of the group are [80, 76, 48]. The complete list of papers follows, [147, 78, 79, 82, 81, 80, 83, 42, 76, 43, 47, 48].

Paper on abstraction of biochemical reaction systems, [46].

**Papers on reach control by the Control Research Group of the University of Toronto** The main investigator of the group is M.E. Broucke. [126, 127, 108, 109, 26, 25, 27, 110, 134, 84, 85, 29, 3, 88, 87, 135, 28, 149, 89, 86, 115, 102, 148]

**Control engineering problems for a piecewise-affine hybrid system** [5, 10, 94, 149, 148].

**Papers on control of PAHSP by other research groups** [94, 154].

**Papers on Control and Verification by a research group of Boston University** The main investigator of this group is C. Belta. [11, 7, 8, 10, 9, 77, 75].

**Papers by the Control Research Group of Aalborg University** The main investigator of the group is R. Wisniewski. [18, 103, 136, 106]. Control to facet problems for polynomial systems, [136].

### 3 Control of Hybrid Systems – General References

**Papers on piecewise-linear hybrid systems** The following papers by E.D. Sontag focus attention on the class of piecewise-affine hybrid system on polytopes as a class of hybrid systems for which theoretical progress and effective computations were possible. [138, 140, 141].

**Related papers on control of continuous-time hybrid systems** [2, 55, 111].

**Papers on control of linear or affine systems** [15, 16, 17, 32, 33, 74, 73].

**Stability of piecewise-affine hybrid systems** [].

**Papers on discrete-time piecewise-affine hybrid systems by an ETH research group** The main investigators were A. Bemporad and M. Morari. The restriction here is to discrete-time systems rather than the continuous-time systems investigated in most other references of this list. [12, 13]

**Control of discrete-time linear systems with input constraints** [51].

**Decidability or undecidability of control of hybrid systems** [92, 137, 140].

### 4 Observability and Observers of Piecewise-Affine Hybrid Systems

**Observers of piecewise-affine hybrid systems** The main investigators are Elena De Santis and Marika Di Benedetto. A tutorial paper, [132].

**Papers on observability by the CWI Research Group Control and System Theory** [45, 44].

### 5 Invariant and Controlled-Invariant Subsets of the State Space

**Invariant Subspaces** For invariant subspace of ordinary linear systems see the classical book, [152, 153].

**Invariant Polyhedral Sets** [90, 145].

**Invariant Sets – General Case** [19, 65, 96, 116, 118, 155].

**Controlled-Invariant Subspaces** For controlled-invariant sets of ordinary linear systems see the classical book, [152, 153].

**Controlled-Invariant Subsets** Papers by P.O. Gutman et al, [74].  
Papers by F. Blanchini et al., [19, 20, 21, 23].  
Papers by E. De Santis et al., [129, 130, 131].  
Papers by others, [14, 69, 70, 91, 104, 146, 156].

## 6 Papers on Abstraction of Piecewise-Affine Hybrid Systems

**Papers by an INRIA Research Group** The main investigator is H. de Jong. [53, 54, 52, 6, 125].

**Papers by a research group of Boston University** The main investigator is C. Belta. [7, 75].

**Papers by a Research Group of Masaryk University Brno** The main investigator is David Safranek who teaches a course on bioinformatics. [46].

**Papers on abstraction of piecewise-affine systems** [4].

## 7 Realization Theory of Hybrid Systems

**Realization theory** Realization of hybrid systems is discussed. Realization of hybrid systems on polytopes is not discussed in the following papers. [121, 120, 122, 119].

## 8 Piecewise-linear systems

**Publications of UCB research group** In able to investigate the class of nonlinear systems in particular models of circuits, the class of piecewise-linear systems was considered at UC Berkeley. The main investigator was E.S. Kuh. [60, 61]. An even earlier paper is [99]. A related paper is [97].

**Publications of another UCB research group** Subsequently the class of piecewise-linear systems was investigated more deeply at UC Berkeley by Leon Chua and co-workers. The main investigator was L.O. Chua. [34, 39, 35, 37, 36, 38, 100, 101].

## 9 Background References in Control Theory and in Control Engineering

**Books on control engineering** Control engineering books include [56, 59].

**Books on control theory** An elementary introduction to control theory for researchers from outside control, is the book [1].

Books on linear systems are [31, 98]. A book written for readers both of control and of computer science is the book, [117]. For mathematical control theory see the book, [142]

**Books on hybrid systems and switched systems** [67, 107, 112, 144].

**Books and articles on discontinuous systems and their control** [40, 49].

## **10 Convexity and Polytopes**

**Convexity** [124, 151, 22].

**Polytopes** Books on polytopes are [24, 68, 71, 72, 114, 157]

Articles on polytopes include, [30, 66, 133].

**Triangulations of polytopes** [50, 58, 105].

**Projections of polytopes** [123].

**Piecewise-linear algebra** [139].

**Papers on Packages for Computations with Polytopes** [62, 64, 63, 143].

## **11 Background References in Mathematics**

**Differential equations** [41, 93, 150]

**Filippov solution of a discontinuous ordinary differential equation** [57].

**Piecewise-linear topology** [95, 113, 128].

## References

- [1] Pedro Albertos and Iven Mareels. *Feedback and control for everyone*. Springer, Berlin, 2010. control for researchers outside control area.
- [2] E. Asarin, O. Bournez, T. Dang, and O. Maler. Approximate reachability analysis of piecewise-linear hybrid systems. In N. Lynch and B.H. Krogh, editors, *Hybrid Systems: Computation and Control*, volume 1790 of *Lecture Notes in Computer Science*, pages 20–31, Berlin, 2000. Springer.
- [3] Graeme Ashford and Mireille E. Broucke. Time-varying affine feedback for reach control on simplices. *Automatica*, 49:1365–1369, 2013.
- [4] Shun-ichi Azuma, Eriko Yanagisawa, and Jun-ichi Imura. Controllability analysis of biosystems based on piecewise-affine systems approach. *IEEE Transactions on Automatic Control and IEEE Transactions on Circuits and Systems*, 21:864 – 874, 2005.
- [5] Andrea Balluchi, Federico Di Natale, Alberto Sangiovanni-Vincenteli, and Jan H. van Schuppen. Synthesis for idle speed control of an automotive engine. In Rajeev Alur and George J. Pappas, editors, *Hybrid Systems: Computation and Control*, number 2993 in *Lecture Notes in Computer Science*, pages 80–94, Berlin, 2004. Springer.
- [6] G. Batt, D. Ropers, H. de Jong, J. Geiselmann, R. Mateescu, M. Page, and D. Schneider. Validation of qualitative models of genetic regulatory networks by model checking: Analysis of the nutritional stress response in *Escherichia coli*. *Bioinformatics*, 21 (Supp.1):i19–i28, 2005.
- [7] C. Belta, P. Finin, L.C.G.J.M. Habets, A.M. Halasz, M. Imielinski, R.V. Kumar, and H. Rubin. Understanding the bacterial stringent response using reachability analysis of hybrid systems. In R. Alur and G.J. Pappas, editors, *Hybrid Systems: Computation and Control, Proceedings of the 7th International Workshop on Hybrid Systems - Computation and Control (HSCC 2004)*, volume 2993 of *Lecture Notes in Computer Science*, pages 111–125, Berlin, 2004. Springer.
- [8] C. Belta and L.C.G.J.M. Habets. Constructing decidable hybrid systems with velocity bounds. In R. Alur and G.J. Pappas, editors, *Proceedings of the 43th IEEE Conference on Decision and Control*, New York, 2004. IEEE Press.
- [9] C. Belta and L.C.G.J.M. Habets. Controlling a class of nonlinear systems on rectangles. *IEEE Trans. Automatic Control*, 51:1749–1759, 2006.
- [10] C. Belta, V. Isler, and G. Pappas. Discrete abstractions for robot planning and control in polygonal environments. *IEEE Trans. Robotics*, 21:864–874, 2005.
- [11] Calin Belta, Luc C.G.J.M. Habets, and Vijay Kumar. Control of multi-affine systems on rectangles with applications to hybrid biomolecular networks. In *Proceedings of the 41st IEEE Conference on Decision and Control*, pages 534–539, New York, 2002. IEEE Press.
- [12] A. Bemporad, G. Ferrari-Trecate, and M. Morari. Observability and controllability of piecewise affine and hybrid systems. *IEEE Trans. Automatic Control*, 45:1864–1876, 2000.
- [13] A. Bemporad and M. Morari. Control of systems integrating logic, dynamics, and constraints. *Automatica*, 35:407–427, 1999.
- [14] A. Bemporad, M. Morari, V. Dua, and E.N. Pistikopoulos. The explicit linear quadratic regulator for constrained systems. *Automatica*, 38:3–20, 2002.
- [15] A. Benzaouia and A. Hmamed. Regulator problem for linear continuous-time systems with nonsymmetrical constrained control. *IEEE Trans. Automatic Control*, 38:1556–1560, 1993.
- [16] L. Berardi, E. De Santis, and M.D. Di Benedetto. Control of switching systems under state and input constraints. In *Proc. European Control Conference (ECC99)*, 1999.
- [17] D.P. Bertsekas and I.B. Rhodes. On the minmax reachability of target set and target tubes. *Automatica*, 7:233–247, 1971.
- [18] Jakob Bjørn, Morten Kjaergaard, and Martin Sorensen. *Autonomous hover flight for a quad rotor helicopter*. PhD thesis, Aalborg University, Aalborg, 2007.
- [19] F. Blanchini. Set invariance in control - A survey. *Automatica*, 35:1747–1768, 1999.
- [20] F. Blanchini and F.A. Pellegrino. Relatively optimal control and its linear implementation. *IEEE Trans. Automatic Control*, 48:2151–2162, 2003.
- [21] F. Blanchini and F.A. Pellegrino. Relatively optimal control: A static piecewise affine solution. *SIAM J. Control & Opt.*, 46:585–603, 2007.
- [22] Stephen Boyd and Lieven Vandenberghe. *Convex optimization*. Cambridge University Press, Cambridge, U.K., (with corrections) edition, 2007.
- [23] H. Brezis. On a characterization of flow-invariant sets. *Comm. Pure and Appl. Math.*, 23:261–263, 1970.
- [24] A. Brøndsted. *An introduction to convex polytopes*. Springer-Verlag, Berlin, 1983.
- [25] M.E. Broucke. On the reach control indices of affine systems on simplices. In *Proc. 8th IFAC Symposium on Nonlinear Control Systems (NOLCOS.2010)*, pages 96–101, 2010.

- [26] Mireille E. Broucke. Reach control on simplices by continuous state feedback. *SIAM J. Control & Opt.*, 48:3482–3500, 2010.
- [27] Mireille E. Broucke and Marcus Ganness. Reach control on simplices by piecewise affine feedback. In *Proc. 2011 Automatic Control Conference (ACC.2011)*, pages 2633–2638, 2011.
- [28] Mireille E. Broucke and Marcus Ganness. Reach control on simplices by piecewise affine feedback. *SIAM J. Control & Opt.*, 52:3261–3286, 2014.
- [29] Mireille E. Broucke and Elham Semsar-Kazerooni. Reach control problem: Well-posedness and structural stability. In *Proc. 51st IEEE Conference on Decision and Control*, pages 4205–4210, New York, 2012. IEEE Press.
- [30] B. Büeler, A. Enge, and K. Fukuda. Exact volume computation for polytopes: A practical study. In G. Kalai and G.M. Ziegler, editors, *Polytopes – Combinatorics and computation*, pages 131–154. Birkhäuser, Basel, 1998.
- [31] F.M. Callier and C.A. Desoer. *Linear system theory*. Springer-Verlag, New York, 1991.
- [32] E.B. Castelan and J.C. Hennes. Eigenstructure assignment for state constrained linear continuous-time systems. *Automatica*, 28:605–611, 1992.
- [33] E.B. Castelan and J.C. Hennes. On invariant polyhedra of continuous-time linear systems. *IEEE Trans. Automatic Control*, 38:1680–1685, 1993.
- [34] L.O. Chua. Section-wise piecewise linear functions: Canonical representation, properties and applications. *Proc. IEEE*, 65:915–929, 1977.
- [35] L.O. Chua and A. Deng. Canonical piecewise linear analysis: Part ii – tracing driving point and transfer characteristics. *IEEE Trans. Circuits & Systems*, 32:417–443, 1985.
- [36] L.O. Chua and A. Deng. Canonical piecewise linear analysis: Generalised breaking point hopping algorithm. *Circuit Theory and Appl.*, 14:35–52, 1986.
- [37] L.O. Chua and A. Deng. Canonical piecewise linear modeling. *IEEE Trans. Circuits & Systems*, 33:511–525, 1986.
- [38] L.O. Chua and A. Deng. Canonical piecewise linear representation. *IEEE Trans. Circuits & Systems*, 35:101–111, 1988.
- [39] L.O. Chua and R.L.P. Ying. Canonical piecewise linear analysis. *IEEE Trans. Circuits & Systems*, 30:125–140, 1983.
- [40] F.H. Clarke, Y.S. Ledyaev, R.J. Stern, and P.R. Wolenski. *Nonsmooth analysis and control theory*. Number 178 in Graduate Texts in Mathematics. Springer, Berlin, 1998.
- [41] E.A. Coddington and N. Levinson. *The theory of ordinary differential equations*. McGraw-Hill Book Co., New York, 1955.
- [42] Pieter Collins, Luc Habets, Anton Kuut, Margreet Nool, Mihály Petreczky, and Jan H. van Schuppen. Conpahs – A software package for control of piecewise-affine hybrid systems. In *Proceedings Computer Aided Control System Design (CACSD.2006)*, page to appear, New York, 2006. IEEE Press.
- [43] Pieter Collins, Luc C.G.J.M. Habets, and Jan H. van Schuppen. Control to facet by piecewise-affine output feedback. In *Proc. International Symposium MTNS (MTNS.2008)*. Virginia Institute of Technology, 2008.
- [44] Pieter Collins and Jan H. van Schuppen. Observability of hybrid systems and turing machines. In *Proceedings of the 43th IEEE Conference on Decision and Control*, pages 7–12, New York, 2004. IEEE Press.
- [45] Pieter Collins and Jan H. van Schuppen. Observability of piecewise-affine hybrid systems. In Rajeev Alur and George J. Pappas, editors, *Hybrid Systems: Computation and Control*, number 2993 in Lecture Notes in Computer Science, pages 265–279, Berlin, 2004. Springer.
- [46] Pieter J. Collins, Luc Habets, Jan H. van Schuppen, Ivana Černá, Jana Fabriková, and David Šafránek. Abstraction of biochemical reaction systems on polytopes. In *Proc. IFAC World Congress (IFAC.WC.2011)*, Laxenburg, 2011. IFAC, IFAC.
- [47] Pieter J. Collins, Luc C.G.J.M. Habets, Mihály Petreczky, and Jan H. van Schuppen. Control of piecewise-affine hybrid systems - Extended abstract. In A. Giua, C. Mahulea, M. Silva, and J. Zaytoon, editors, *Preprints of the 3rd IFAC Conference on Analysis and Design of Hybrid systems (ADHS)*, pages 234–237, Laxenburg, 2009. IFAC, IFAC.
- [48] Pieter J. Collins, Luc C.G.J.M. Habets, and Jan H. van Schuppen. Control to facet by piecewise-affine output feedback. *IEEE Trans. Automatic Control*, 57:2831–2843, 2012.
- [49] J. Cortés. Discontinuous dynamical systems – A tutorial on solutions, nonsmooth analysis, and stability. *IEEE Control Systems Magazine*, 28:36–73, 2008.
- [50] R.W. Cottle. Minimal triangulation of the 4-cube. *Discrete Mathematics*, 40:25–29, 1982.
- [51] P.D’Alessandro and E. De Santis. Reachability in input constrained discrete-time linear systems. *Automatica*, 28:227–229, 1992.
- [52] H. de Jong, J. Geiselmann, G. Batt, C. Hernandez, and M. Page. Qualitative simulation of the initiation of sporulation in *bacillus subtilis*. *Bulletin of Mathematical Biology*, 66:261–300, 2004.
- [53] H. de Jong, J. Geiselmann, C. Hernandez, and M. Page. Genetic network analyzer: Qualitative simulation of genetic regulatory networks. *Bioinformatics*, 19:336–344, 2003.
- [54] Hidde de Jong, Jean-Luc Gouzé, Céline Hernandez, Michel Page, Tewfik Sari, and Johannes Geiselman. Qualitative simulation of genetic regulatory networks using piecewise-linear models. *Bull. Math. Biology*, 66:301–340, 2004.

- [55] A. Deshpande and P. Varaiya. Viable control of hybrid systems. In P. Antsaklis, W. Kohn, A. Nerode, and S. Sastry, editors, *Hybrid systems II*, volume 999 of *Lecture Notes in Computer Science*, pages 128–147, Berlin, 1995. Springer.
- [56] Richard C. Dorf and Robert H. Bishop. *Modern control systems*. Pearson – Prentice Hall, Upper Saddle River, 10th edition edition, 2005.
- [57] A.F. Filippov. *Differential equations with discontinuous right-hand side*. Number 42 in American Mathematical Society Translations - Series 2. American Mathematical Society, Michigan, 1964.
- [58] S. Fortune. Voronoi diagrams and Delaunay triangulations. In J.E. Goodman and J. O’Rourke, editors, *Handbook of discrete and computational geometry*, pages 377–388. CRC Press, Boca Raton, 1997.
- [59] G.F. Franklin, J.D. Powell, and A. Emami-Naeini. *Feedback control of dynamic systems, 3rd Ed.* Addison-Wesley Company, Reading, MA, 1994.
- [60] T. Fujisawa and E.S. Kuh. Piecewise-linear theory of nonlinear networks. *SIAM J. Appl. Math.*, 22:307–328, 1972.
- [61] T. Fujisawa, E.S. Kuh, and T. Ohtsuki. A sparse matrix method for analysis of piecewise-linear resistive networks. *IEEE Trans. Circuit Theory*, 19:571–584, 1972.
- [62] K. Fukuda. CDD program package. Computer program library, see [http://www.ifor.math.ethz.ch/~fukuda/cdd\\_home/cdd.html](http://www.ifor.math.ethz.ch/~fukuda/cdd_home/cdd.html), ETHZ, Zürich, 2000.
- [63] K. Fukuda. Frequently asked questions in polyhedral computation. Report <http://www.ifor.math.ethz.ch/~fukuda/polyfaq/polyfaq.html>, ETH, Zürich, 2000.
- [64] Komei Fukuda. CDDlib reference manual. Report version 093a, McGill University, Montréal, Quebec, Canada, 2003.
- [65] T.C. Gard. Strongly flow invariant sets. *Appl. Analysis*, 10:285–293, 1980.
- [66] M. Gerstenhaber. Theory of convex polyhedral cones. In T.J.C. Koopmans, editor, *Activity analysis of production and allocation*, pages 298–316. Wiley & Sons, New York, 1951.
- [67] Rafal Goebel, Ricardo G. Sanfelice, and Andrew R. Teel. *Hybrid dynamical systems - Modeling, stability, and Robustness*. Princeton University Press, Princeton, 2012.
- [68] J.E. Goodman and J. O’Rourke, editors. *Handbook of discrete and computational geometry*. CRC Press, Boca Raton, NY, 1997.
- [69] T.J. Graettinger and B.H. Krogh. Hyperplane method for reachable state estimation for linear time-invariant systems. *J. Optim. Th. & Appl.*, 69:555–588, 1991.
- [70] T.J. Graettinger and B.H. Krogh. On the computation of reference signal constraints for guaranteed tracking performance. *Automatica*, 27:161–165, 1992.
- [71] B. Grünbaum. *Convex polytopes*. Number 16 in Pure and Applied Mathematics. Wiley & Sons, London, 1967.
- [72] B. Grünbaum. *Convex polytopes (2nd. Ed.)*. Number 221 in Graduate Texts in Mathematics. Springer, New York, 2003.
- [73] P.-O. Gutman and M. Cwikel. An algorithm to find maximal state constraint sets for discrete-time linear dynamical systems with bounded controls and states. *IEEE Trans. Automatic Control*, 32:251–254, 1987.
- [74] P.O. Gutman and M. Cwikel. Convergence of an algorithm to find maximal state constraint sets for discrete-time linear dynamical systems with bounded control and states. *IEEE Trans. Automatic Control*, 31:457–459, 1986.
- [75] L.C.G.J.M. Habets and C. Belta. Temporal logic control for piecewise-affine hybrid systems on polytopes. In *Proc. of the 19th International Symposium on Mathematical Theory of Networks and Systems (MTNS 2010)*, pages 195–202, 2010.
- [76] L.C.G.J.M. Habets, P.J. Collins, and J.H. van Schuppen. Reachability and control synthesis for piecewise-affine hybrid systems on simplices. *IEEE Trans. Automatic Control*, 51:938–948, 2006.
- [77] L.C.G.J.M. Habets, M. Kloetzer, and C. Belta. Control of rectangular multi-affine hybrid systems. In *Proc. 45th IEEE Conference on Decision and Control*, pages 2619–2624, New York, 2006. IEEE, IEEE Press.
- [78] L.C.G.J.M. Habets and J.H. van Schuppen. Control of piecewise-linear hybrid system on simplices and rectangles. In M.D. Di Benedetto and A. Sangiovanni-Vincentelli, editors, *Hybrid Systems; Computation and Control*, volume 2034 of *Lecture Notes in Computer Science*, pages 261–274, Berlin, 2001. Springer.
- [79] L.C.G.J.M. Habets and J.H. van Schuppen. A controllability result for piecewise-linear hybrid systems. In *Proceedings of European Control Conference (ECC2001)*, pages 3870–3873, Porto, 2001.
- [80] L.C.G.J.M. Habets and J.H. van Schuppen. A control problem for affine dynamical systems on a full-dimensional polytope. *Automatica*, 40:21–35, 2004.
- [81] L.C.G.J.M. Habets and J.H. van Schuppen. Reachability of affine systems on polytopes in the plane. In *Proceedings International Symposium MTNS.2004 (CD-ROM)*, Leuven, 2004.
- [82] Luc C.G.J.M. Habets and Jan H. van Schuppen. Reduction of affine systems on polytopes. In *Proceedings of the International Symposium MTNS 2002*, 2002.
- [83] Luc C.G.J.M. Habets and Jan H. van Schuppen. Control to facet problems for affine systems on simplices and polytopes - with application to control of hybrid systems. In *Proc. 44th IEEE Conference on Decision and Control*, pages 4175–4180, New York, 2005. IEEE Press.

- [84] M.K. Helwa and M.E. Broucke. Monotonic reach control on polytopes. In *Proc. 50th IEEE Conference on Decision and Control (CDC.2011)*, pages 4741–4746, New York, 2011. IEEE Press.
- [85] M.K. Helwa and M.E. Broucke. Generalized flow conditions for reach control on polytopes. In *Proc. 51th IEEE Conference on Decision and Control*, pages 4199–4204, New York, 2012. IEEE Press.
- [86] M.K. Helwa, Z. Lin, and M.E. Broucke. On the necessity of the invariance conditions for reach control on polytopes. *Systems & Control Lett.*, 90:16–19, 2016.
- [87] Mohamed Helwa. *Reach control problems on polytopes*. PhD thesis, University of Toronto, Toronto, Ontario, Canada, 2013.
- [88] Mohammed K. Helwa and Mireille E. Broucke. Monotonic reach control of polytopes. *IEEE Trans. Automatic Control*, 58:2704–2709, 2013.
- [89] Mohammed K. Helwa and Mireille E. Broucke. Flow functions, control flow functions, and the reach control problem. *Automatica*, 55:108–115, 2015.
- [90] J.C. Hennet. Une extension du lemme de Farkas et son application au probl’eme de régulation lineaire sous contraintes. *Comptes Rendus des Sceances de l’ Academie des Sciences de Paris*, 308 (Series 1):415–419, 1989.
- [91] J.C. Hennet and J.P. Beziat. A class of invariant regulators for the discrete-time linear constrained regulator problem. *Automatica*, 27:549–554, 1991.
- [92] T.A. Henzinger, P.W. Kopke, A. Puri, and P. Varaiya. What’s decidable about hybrid automata. In *Proceedings of the 27th Annual Symposium on Theory of Computing*, pages 373–382, X, 1995. ACM Press.
- [93] M.W. Hirsch and S. Smale. *Differential equations, dynamical systems and linear algebra*. Academic Press, New York, 1974.
- [94] Thomas Erhard Hodrus, Michael Buchholz, and Volker Krebs. A new local control strategy for control of discrete-time piecewise affine systems. In *Proceedings of the 44th IEEE Conference on Decision and Control*, pages 4181–4186, New York, 2005. IEEE Press.
- [95] J. Hudson. *Piecewise linear topology*. University of Chicago Lecture Notes. W.A. Benjamin, New York, 1969.
- [96] V. Hutson and K. Schmitt. Permanence and the dynamics of biological systems. *Math. Biosciences*, 111:1–71, 1992.
- [97] M. Iri. A method of multi-dimensional linear interpolation. *J. Information Processing Soc. of Japan*, 1:211–215, 1967.
- [98] T. Kailath. *Linear systems*. Prentice-Hall Inc., Englewood Cliffs, 1980.
- [99] J. Katzenelson. An algorithm for solving nonlinear resistive networks. *Bell System Techn. J.*, 44:1605–1620, 1965.
- [100] C. Khalert and L.O. Chua. A generalised canonical piecewise linear representation. *IEEE Trans. Circuits & Systems*, 37:373–383, 1990.
- [101] C. Khalert and L.O. Chua. The complete canonical piecewise linear representation - part i: The geometry of the state space. *IEEE Trans. Circuits and Systems - I: Fundamental Theory and Applications*, 39:222–236, 1992.
- [102] Z. Kroeze and M.E. Broucke. A viability approach to the output reach control problem. In *Proc. American Control Conference (ACC.2016)*, pages 6054–6059, New York, 2016. IEEE Press.
- [103] Jesper A. Larsen, Rafael Wisniewski, and J.D. Grunnet. Combinatorial hybrid systems. In *Proc. 2008 IEEE Workshop on Computer Aided Control Systems Design (CACSD.2008)*, pages x–y, New York, 2008. IEEE Press.
- [104] J.B. Lasserre. Reachable, controllable sets and stabilizing control of constrained systems. *Automatica*, 29:531–536, 1993.
- [105] C.W. Lee. Subdivisions and triangulations of polytopes. In J.E. Goodman and J. O’Rourke, editors, *Handbook of discrete and computational geometry*, pages 271–290. CRC Press, Boca Raton, NY, U.S.A., 1997.
- [106] J. Leth and R. Wisniewski. Local analysis of hybrid systems on polyhedral sets with state-dependent switching. *Int. J. Applied Mathematics and Computer Science*, 24:341–355, 2014.
- [107] Daniel Liberzon. *Switching in systems and control*. Systems and Control: Foundations and Applications. Birkhäuser, Boston, 2003.
- [108] Z. Lin and M.E. Broucke. Resolving control to facet problems for affine hypersurface systems on simplices. In *Proc. 45th IEEE Conference on Decision and Control (CDC.2006)*, pages 2625–2630, New York, 2006. IEEE Press.
- [109] Z. Lin and M.E. Broucke. Reachability and control of affine hypersurface systems on polytopes. In *Proc. 46th IEEE Conference on Decision and Control (CDC.2007)*, pages 733–738, New York, 2007. IEEE Press.
- [110] Z. Lin and M.E. Broucke. On a reachability problem for affine hypersurface systems on polytopes. *Automatica*, 47:769–775, 2011.
- [111] J. Lygeros, C. Tomlin, and S. Sastry. Controllers for reachability specifications for hybrid systems. *Automatica*, 35:349–370, 1999.
- [112] A.S. Matveev and A.V. Savkin. *Qualitative theory of hybrid dynamical systems*. Birkhäuser, Boston, 2000.
- [113] J.P. May. *Simplicial objects in combinatorial topology*. University of Chicago Press, Chicago, 1992.
- [114] P. McMullen. The maximum number of faces of a convex polytope. *Mathematica*, 17:179–184, 1970.



- [115] Miad Moarref, Melkior Ornik, and Mireille E. Broucke. An obstruction to solvability of the reach control problem using affine feedback. *Automatica*, 71:229–236, 2016.
- [116] M. Nagumo. Über die Lage der Integralkurven gewöhnlicher Differentialgleichungen. *Proceedings of the Physico-Mathematical Society of Japan*, 24:272–559, 1942.
- [117] L. Padulo and M.A. Arbib. *System theory*. Hemisphere Publishing Corporation, Washington D.C., 1974.
- [118] T. Pecsvaradi and K.S. Narendra. Reachable sets for linear dynamical systems. *Info. Control*, 19:319–344, 1971.
- [119] M. Petreczky and R. Vidal. Realization theory for semi-algebraic hybrid systems. In *Hybrid Systems: Computation and Control 2008*, volume 4981 of *LNCIS*. Springer-Verlag, 2008.
- [120] Mihály Petreczky and Jan H. van Schuppen. Observability reduction of piecewise-affine hybrid systems. In A. Edelmayer, editor, *Proceedings of the International Symposium on the Mathematical Theory of Networks and Systems (MTNS.2010)*, Budapest, 2010. University of Budapest.
- [121] Mihály Petreczky and Jan H. van Schuppen. Realization theory for linear hybrid systems. *IEEE Trans. Automatic Control*, 55:2282 – 2297, 2010.
- [122] Mihaly Petreczky and Jan H. van Schuppen. Partial realization theory for linear switched systems: A formal power series approach. *Automatica*, 47:2177–2184, 2011.
- [123] J. Rambau and G.M. Ziegler. Projections of polytopes and the generalized Baues conjecture. *Discrete Comput. Geometry*, 16:215–237, 1996.
- [124] R.T. Rockafellar. *Convex analysis*. Princeton University Press, Princeton, 1970.
- [125] Delphine Ropers, Hidde de Jong, Michel Page, Dominique Schneider, and Johannes Geiselmann. Qualitative simulation of the carbon starvation response in *escherichia coli*. *BioSystems*, 84:124–152, 2006.
- [126] Bartek Roszak and Mireille E. Broucke. Necessary and sufficient conditions for reachability on a simplex. In *Proc. 44th IEEE Conf. Decision and Control and European Control Conference*, pages 4706–4711, New York, 2005. IEEE Press.
- [127] Bartek Roszak and Mireille E. Broucke. Necessary and sufficient conditions for reachability on a simplex. *Automatica*, 42:1913–1918, 2006.
- [128] C. Rourke and B. Sanderson. *Introduction to piecewise linear topology*. Springer Study Edition. Springer-Verlag, Berlin, 1982.
- [129] E. De Santis. On positively invariant sets for discrete-time linear systems with disturbance: An applications of maximal disturbance sets. *IEEE Trans. Automatic Control*, 39:245–249, 1994.
- [130] E. De Santis. On invariant sets for constrained discrete-time linear systems with disturbances and parametric uncertainties. *Automatica*, 33:2033–2039, 1997.
- [131] E. De Santis, M.D. Di Benedetto, and L. Berardi. Computation of maximal safe sets for switching systems. *IEEE Trans. Automatic Control*, 49:184–195, 2004.
- [132] Elena De Santis and Maria Domenica Di Benedetto. Observability of hybrid dynamical systems. *Foundations and Trends in Systems and Control*, 3:363–540, 2016.
- [133] R. Schneider. *Convex bodies; The Brunn-Minkowski theory*. Number 44 in Encyclopedia of Mathematics and its Applications. Cambridge University Press, Cambridge, 1993. seen 2012:08:27, very good theory.
- [134] E. Semsar-Kazerooni and M.E. Broucke. Reach controllability of single input affine systems. In *Proc. 50th IEEE Conference on Decision and Control (CDC.2011)*, pages 4747–4752, New York, 2011. IEEE Press.
- [135] Elham Semsar-Kazerooni and Mireille E. Broucke. Reach controllability of single input affine systems on a simplex. *IEEE Trans. Automatic Control*, 59:738–744, 2014.
- [136] Christoffer Sloth and Rafael Wisniewski. Control to facet for polynomial systems. In *Proc. HSCC.2014*, pages 123–132. ACM, 2014.
- [137] E.H. Snoussi. Qualitative dynamics of piecewise-linear differential equations: A discrete mapping approach. *Dynamics and Stability of Systems*, 4:189–207, 1989.
- [138] E.D. Sontag. Nonlinear regulation: The piecewise linear approach. *IEEE Trans. Automatic Control*, 26:346–358, 1981.
- [139] E.D. Sontag. Remarks on piecewise-linear algebra. *Pacific J. Math.*, 98:183–201, 1982.
- [140] E.D. Sontag. From linear to nonlinear: Some complexity questions. In *Proceedings of the 34th IEEE Conference on Decision and Control*, pages 2916–2920, New York, 1995. IEEE Press.
- [141] E.D. Sontag. Interconnected automata and linear systems: A theoretical framework in discrete-time. In R. Alur, T. Henzinger, and E.D. Sontag, editors, *Proceedings Workshop on Verification and Control of Hybrid Systems*, pages 436–448, Berlin, 1996. Springer.
- [142] E.D. Sontag. *Mathematical control theory: Deterministic finite dimensional systems (2nd. Ed.)*. Number 6 in Graduate Text in Applied Mathematics. Springer, New York, 1998.
- [143] G. Swart. Finding the convex hull facet by facet. *J. Algorithms*, 6:17–48, 1985.

- [144] Paulo Tabuada. *Verification and control of hybrid systems - A symbolic approach*. Springer, New York, 2009.
- [145] S. Tarbouriech and C. Burgat. Positively invariant sets for constrained continuous-time systems with cone properties. *IEEE Trans. Automatic Control*, 39:401–405, 1994.
- [146] S. Tarbouriech and J.C. Hennes. Control of constrained systems. *IEEE Trans. Automatic Control*, 41:1650–1656, 1997.
- [147] J.H. van Schuppen. A sufficient condition for controllability of a class of hybrid systems. In T.A. Henzinger and S. Sastry, editors, *Hybrid systems: Computation and control*, number 1386 in Lecture Notes in Computer Science, pages 374–383, Berlin, 1998. Springer.
- [148] M. Vukosavljev, I. Jansen, M.E. Broucke, and A.P. Schoellig. Safe and robust robot manoeuvres based on reach control. In *Proc. 26th IEEE Conference on Robotics and Automation*, pages 5677–5682, New York, 2016. IEEE Press.
- [149] Marijan Vukosavljev and Mireille E. Broucke. Control of a gantry crane: A reach control approach. In *Proc. 53rd IEEE Conference Decision and Control*, pages 3609–3614, New York, 2014. IEEE Press.
- [150] W. Walter. *Ordinary differential equations*. Number 182 in Graduate Texts in Mathematics. Springer, Berlin, 1998.
- [151] R. Webster. *Convexity*. Oxford University Press, Oxford, 1994.
- [152] W.M. Wonham. *Linear multivariable control: A geometric approach*, volume 101 of *Lecture Notes in Economics and Mathematical Systems*. Springer-Verlag, Berlin, 1974.
- [153] W.M. Wonham. *Linear multivariable control: A geometric approach*. Springer-Verlag, Berlin, 1979.
- [154] Yuhu Wu and Tielong Shen. Reach control problem for linear differential inclusion systems on simplices. *IEEE Trans. Automatic Control*, 61:1403–1408, 2016.
- [155] J.A. Yorke. Invariance for ordinary differential equations. *Math. Systems Theory*, 1:353–372, 1968.
- [156] Q.J. Zhu, N. Zhang, and Y. He. Algorithm for determining the reachability set of a linear control system. *J. Optim. Th. Appl.*, 72:333–353, 1992.
- [157] G.M. Ziegler. *Lectures on polytopes*. Number 152 in Graduate Texts in Mathematics. Springer, Berlin, 1995.